Contents lists available at ScienceDirect



Applied Mathematics and Computation

journal homepage: www.elsevier.com/locate/amc

Some mean value theorems for integrals on time scales

Quốc-Anh Ngô*

Department of Mathematics, College of Science, Viêt Nam National University, Hà Nôi, Viêt Nam Department of Mathematics, National Univesity of Singapore, 2 Science Drive 2, Singapore 117543, Singapore

ARTICLE INFO

Keywords: Inequality Time scales Integral Mean value theorem

ABSTRACT

In this short paper, we present time scales version of mean value theorems for integrals in the single variable case.

© 2009 Elsevier Inc. All rights reserved.

1. Introduction and preliminaries

The following two mean value theorems for time scales are due to M. Bohner and G. Guseinov.

Theorem A (See [1], Theorem 4.1). Suppose that f is continuous on [a,b] and has a delta derivative at each point of [a,b). If f(a) = f(b), then there exist points $\xi, \eta \in [a,b)$ such that

 $f^{\Delta}(\xi) \leq \mathbf{0} \leq f^{\Delta}(\eta).$

Theorem B (See [1], Theorem 4.2). Suppose that f is continuous on [a, b] and has a delta derivative at each point of [a, b). If f(a) = f(b), then there exist points $\xi, \eta \in [a, b)$ such that

 $f^{\Delta}(\xi)(b-a) \leq f(b) - f(a) \leq f^{\Delta}(\eta)(b-a).$

Motivated by Theorem A, the main aim of this paper is to present time scale version of mean value results for integrals in the single variable case. We first introduce some preliminaries on time scales (see [2,3,5] for details).

Definition 1. A time scale T is an arbitrary nonempty closed subset of real numbers.

The calculus of time scales was initiated by Stefan Hilger in his PhD thesis [4] in order to create a theory that can unify discrete and continuous analysis. Let \mathbb{T} be a time scale. \mathbb{T} has the topology that it inherits from the real numbers with the standard topology.

Definition 2. Let $\sigma(t)$ and $\rho(t)$ be the forward and backward jump operators in \mathbb{T} , respectively. For $t \in \mathbb{T}$, we define the forward jump operator $\sigma : \mathbb{T} \to \mathbb{T}$ by

$$\sigma(t) = \inf \{ s \in \mathbb{T} : s > t \},\$$

while the backward jump operator $\rho : \mathbb{T} \to \mathbb{T}$ is defined by

$$\rho(t) = \sup \{ s \in \mathbb{T} : s < t \}.$$

If $\sigma(t) > t$, then we say that *t* is right-scattered, while if $\rho(t) < t$ then we say that *t* is left-scattered.

^{*} Address: Department of Mathematics, College of Science, Viêt Nam National University, Hà Nôi, Viêt Nam. *E-mail address*: bookworm_vn@yahoo.com

^{0096-3003/\$ -} see front matter @ 2009 Elsevier Inc. All rights reserved. doi:10.1016/j.amc.2009.03.025

In this definition we put $\inf \emptyset = \sup \mathbb{T}$ (i.e., $\sigma(t) = t$ if \mathbb{T} has a maximum t) and $\sup \emptyset = \inf \mathbb{T}$ (i.e., $\rho(t) = t$ if \mathbb{T} has a minimum t), where \emptyset denotes the empty set.

Points that are right-scattered and left-scattered at the same time are called isolated. If $\sigma(t) = t$ and $t \neq \sup \mathbb{T}$, then t is called *right-dense*, and if $\rho(t) = t$ and $t \neq \inf \mathbb{T}$, then t is called *left-dense*. Points that are right-dense and left-dense at the same time are called dense.

Definition 3. Let $t \in \mathbb{T}$, then two mappings $\mu, \nu : \mathbb{T} \to [0, +\infty)$ satisfying

$$\mu(t) := \sigma(t) - t, \quad v(t) := t - \rho(t)$$

are called the graininess functions.

We now introduce the set \mathbb{T}^{κ} which is derived from the time scales \mathbb{T} as follows. If \mathbb{T} has a left-scattered maximum *t*, then $\mathbb{T}^{\kappa} := \mathbb{T} - \{t\}$, otherwise $\mathbb{T}^{\kappa} := \mathbb{T}$.

Definition 4. Let $f : \mathbb{T} \to \mathbb{R}$ be a function on time scales. Then for $t \in \mathbb{T}^{\kappa}$, we define $f^{\Delta}(t)$ to be the number, if one exists (finite), such that for all $\varepsilon > 0$ there is a neighborhood U of t such that for all $s \in U$

 $\left|f(\sigma(t)) - f(s) - f^{\Delta}(t)(\sigma(t) - s)\right| \leq \varepsilon |\sigma(t) - s|.$

We say that *f* is Δ -differentiable on \mathbb{T}^{κ} provided $f^{\Delta}(t)$ exists for all $t \in \mathbb{T}^{\kappa}$.

Assume that $f : \mathbb{T} \to \mathbb{R}$ is a function and let $t \in \mathbb{T}^{\kappa}$ ($t \neq \min \mathbb{T}$). Then we have the following

(i) If f is Δ -differentiable at t, then f is continuous at t.

(ii) If *f* is left continuous at *t* and *t* is right-scattered, then *f* is Δ -differentiable at *t* with

$$f^{\Delta}(t) = \frac{f(\sigma(t)) - f(t)}{\mu(t)}.$$

(iii) If *t* is right-dense, then *f* is Δ -differentiable at *t* if and only if

$$\lim_{s\to t}\frac{f(t)-f(s)}{t-s},$$

exists a finite number. In this case

$$f^{\Delta}(t) = \lim_{s \to t} \frac{f(t) - f(s)}{t - s}.$$

(iv) If f is Δ -differentiable at t, then

$$f(\sigma(t)) = f(t) + \mu(t)f^{\Delta}(t).$$

Proposition 1 (See [2], Theorem 1.20). Let $f, g : \mathbb{T} \to \mathbb{R}$ be differentiable at $t \in \mathbb{T}^{\kappa}$. Then

$$(fg)^{\Delta}(t) = f^{\Delta}(t)g(t) + f(\sigma(t))g^{\Delta}(t) = f(t)g^{\Delta}(t) + f^{\Delta}(t)g(\sigma(t))$$

Definition 5. A mapping $f : \mathbb{T} \to \mathbb{R}$ is called *rd-continuous* provided if it satisfies

(1) *f* is continuous at each right-dense point.

(2) The left-sided limit $\lim_{s\to t-f} f(s) = f(t-)$ exists at each left-dense point t of \mathbb{T} .

Remark 1. It follows from Theorem 1.74 of Bohner and Peterson [2] that every rd-continuous function has an antiderivative.

Definition 6. A function $F : \mathbb{T} \to \mathbb{R}$ is called a Δ -antiderivative of $f : \mathbb{T} \to \mathbb{R}$ provided $f^{\Delta}(t) = f(t)$ holds for all $t \in \mathbb{T}^{\kappa}$. Then the Δ -integral of f is defined by

$$\int_a^b f(t)\Delta t = F(b) - F(a).$$

Proposition 2 (See [2], Theorem 1.77). Let f, g be rd-continuous, $a, b, c \in \mathbb{T}$ and $\alpha, \beta \in \mathbb{R}$. Then

(1) $\int_{a}^{b} (\alpha f(t) + \beta g(t))\Delta t = \alpha \int_{a}^{b} f(t)\Delta t + \beta \int_{a}^{b} g(t)\Delta t,$ (2) $\int_{a}^{b} f(t)\Delta t = -\int_{b}^{a} f(t)\Delta t,$ (3) $\int_{a}^{b} f(t)\Delta t = \int_{a}^{c} f(t)\Delta t + \int_{c}^{b} f(t)\Delta t,$

(4) $\int_a^a f(t)\Delta t = 0.$

Definition 7. We say that a function $p : \mathbb{T} \to \mathbb{R}$ is regressive provided

$$1 + \mu(t)p(t) \neq 0, \quad \forall t \in \mathbb{T}^{\kappa}$$

holds.

Definition 8. If a function *p* is regressive, then we define the exponential function by

$$e_p(t,s) = \exp\left(\int_s^t \xi_{\mu(\tau)}(p(\tau))\Delta \tau\right), \quad \forall s,t \in \mathbb{T}$$

where $\xi_h(z)$ is the cylinder transformation which is defined by

$$\zeta_h(\tau) = \begin{cases} \frac{1}{h} \text{Log}(1+\tau h), & \text{if } h > 0, \\ \tau, & \text{if } h = 0, \end{cases}$$

where Log is the principal logarithm function.

Remark 2. It is obviously to see that $e_1(t,s)$ is well-defined and $e_1(t,s) > 0$ for all $t, s \in \mathbb{T}$.

We now list here two properties of $e_p(t,s)$ which we will use in the rest of this paper.

Theorem C (See [2], Theorem 2.33). If p is regressive, then for each $t_0 \in \mathbb{T}$ fixed, $e_p(t, s)$ is a solution of the initial value problem

 $y^{\Delta} = p(t)y, \quad y(t_0) = 1$

on \mathbb{T} .

Theorem D (See [2], Theorem 2.36). If p is regressive, then

(1) $e_p(t,s) = \frac{1}{e_p(s,t)}$. (2) $(\frac{1}{e_p(t,s)})^{\Delta t} = \frac{-p}{e_p(\sigma(t),s)}$.

Throughout this paper, we suppose that \mathbb{T} is a time scale, $a, b \in \mathbb{T}$ with a < b and an interval means the intersection of real interval with the given time scale.

2. Main results

Theorem 1. Let *f* be a continuous function on [*a*, *b*] such that

$$\int_a^b f(x) \Delta x = 0.$$

Then there exist $\xi, \eta \in [a, b)$ so that

$$f(\xi) \leq \int_a^{\xi} f(x) \Delta x, \quad \int_a^{\eta} f(x) \Delta x \leq f(\eta).$$

Proof of Theorem 1. Let

$$h(x) = e_1(a,x) \int_a^x f(t)\Delta t, \quad x \in [a,b).$$

Then

$$\begin{split} h^{\Delta}(x) &= \left(e_1(a,x)\int_a^x f(t)\Delta t\right)^{\Delta} = (e_1(a,x))^{\Delta}\int_a^x f(t)\Delta t + e_1(a,\sigma(x))\left(\int_a^x f(t)\Delta t\right)^{\Delta} \\ &= \left(\frac{1}{e_1(x,a)}\right)^{\Delta}\int_a^x f(t)\Delta t + e_1(a,\sigma(x))\left(\int_a^x f(t)\Delta t\right)^{\Delta} = \frac{-1}{e_1(\sigma(x),x)}\int_a^x f(t)\Delta t + e_1(a,\sigma(x))f(x) \\ &= -e_1(a,\sigma(x))\int_a^x f(t)\Delta t + e_1(a,\sigma(x))f(x). \end{split}$$

Since h(a) = h(b) then there exists $\xi, \eta \in [a, b)$ such that

$$h^{\Delta}(\xi) \leq 0 \leq h^{\Delta}(\eta).$$

Hence

$$-e_1(a,\sigma(\xi))\int_a^{\xi}f(t)\Delta t + e_1(a,\sigma(\xi))f(\xi) \leq 0 \leq -e_1(a,\sigma(\eta))\int_a^{\eta}f(t)\Delta t + e_1(a,\sigma(\eta))f(\eta),$$

which implies that

$$f(\xi) \leq \int_a^{\xi} f(x) \Delta x, \quad \int_a^{\eta} f(x) \Delta x \leq f(\eta).$$

The proof is complete. \Box

Theorem 2. Let f be a continuous function on [a, b] such that

$$\int_a^b f(x) \Delta x = 0.$$

Then there exist $\xi, \eta \in [a, b)$ so that

$$\frac{e_1(a,\xi)}{e_1(a,\sigma(\xi))}f(\xi) \leq \int_a^{\sigma(\xi)} f(t)\Delta t,$$

and

$$\int_{a}^{\sigma(\eta)} f(t) \Delta t \leq \frac{e_1(a,\eta)}{e_1(a,\sigma(\eta))} f(\eta).$$

Proof of Theorem 2. Let

$$h(x) = e_1(a, x) \int_a^x f(t) \Delta t.$$

Then

$$h^{\Delta}(x) = e_1(a,x)f(x) - e_1(a,\sigma(x))\int_a^{\sigma(x)} f(t)\Delta t.$$

Since h(a) = h(b) then there exists $\xi, \eta \in [a, b)$ such that

$$g^{\Delta}(\xi) \leqq \mathbf{0} \leqq g^{\Delta}(\eta).$$

Hence

$$e_1(a,\xi)f(\xi) - e_1(a,\sigma(\xi))\int_a^{\sigma(\xi)} f(t)\Delta t \leq 0 \leq e_1(a,\eta)f(\eta) - e_1(a,\sigma(\eta))\int_a^{\sigma(\eta)} f(t)\Delta t,$$

which implies that

$$\frac{e_1(a,\xi)}{e_1(a,\sigma(\xi))}f(\xi) \leq \int_a^{\sigma(\xi)} f(t)\Delta t,$$
$$\int_a^{\sigma(\eta)} f(t)\Delta t \leq \frac{e_1(a,\eta)}{e_1(a,\sigma(\eta))}f(\eta).$$

The proof is complete. \Box

Corollary 1. Let $\mathbb{T} = \mathbb{R}$, from Theorems 1 and 2 together with the continuity of *f* we deduce that the existence of $\gamma \in [a, b]$ such that

$$f(\gamma) = \int_a^{\gamma} f(x) \mathrm{d}x$$

provided

$$\int_a^b f(x) \mathrm{d}x = 0.$$

Theorem 3. Let f be a continuous function on [a, b] such that

$$\int_a^b f(x) \Delta x = 0.$$

Then for each $\mathbb{T} \ni c < a$, there exist $\xi, \eta \in [a, b)$ so that

$$f(\xi)(\xi-c) \leq \int_a^{\xi} f(t)\Delta t, \quad \int_a^{\eta} f(t)\Delta t \leq f(\eta)(\eta-c)$$

Proof of Theorem 3. Let

$$h(x) = \frac{1}{x-c} \int_a^x f(t) \Delta t, \quad x \in [a,b), \ \mathbb{T} \ni c < a.$$

Therefore

$$h^{\Delta}(x) = \frac{-1}{(\sigma(x)-c)(x-c)} \int_a^x f(t)\Delta t + \frac{1}{\sigma(x)-c}f(x).$$

Since h(a) = h(b) then there exists $\xi, \eta \in [a, b)$ such that

$$h^{\Delta}(\xi) \leq 0 \leq h^{\Delta}(\eta).$$

Hence

$$\frac{-1}{(\sigma(\xi)-c)(\xi-c)}\int_a^{\xi}f(t)\Delta t + \frac{1}{\sigma(\xi)-c}f(\xi) \leq 0 \leq \frac{-1}{(\sigma(\eta)-c)(\eta-c)}\int_a^{\eta}f(t)\Delta t + \frac{1}{\sigma(\eta)-c}f(\eta),$$

which implies

$$\frac{f(\xi)}{\sigma(\xi) - c} \leq \frac{\int_a^{\xi} f(t) \Delta t}{(\sigma(\xi) - c)(\xi - c)}, \\ \frac{\int_a^{\eta} f(t) \Delta t}{(\sigma(\eta) - c)(\eta - c)} \leq \frac{f(\eta)}{\sigma(\eta) - c}$$

Thus

$$f(\xi)(\xi-c) \leq \int_a^{\xi} f(t)\Delta t, \quad \int_a^{\eta} f(t)\Delta t \leq f(\eta)(\eta-c).$$

The proof is complete. $\hfill\square$

Corollary 2. Let $\mathbb{T} = \mathbb{R}$, from Theorem 3 together with the continuity of *f* we deduce the existence of $\gamma \in [a, b]$ such that

$$f(\gamma)(\xi-c) = \int_a^{\gamma} f(x) \mathrm{d}x$$

for each c < a provided

$$\int_a^b f(x) \Delta x = 0.$$

Theorem 4. Let f, g be a continuous function on [a, b]. Then there exist ξ , $\eta \in [a, b)$ so that

$$f(\xi)\left(\int_{\xi}^{b} g(t)\Delta t\right) \leq \left(\int_{a}^{\sigma(\xi)} f(t)\Delta t\right)g(\xi),$$

and

$$f(\eta)\left(\int_{\eta}^{b} g(t)\Delta t\right) \ge \left(\int_{a}^{\sigma(\eta)} f(t)\Delta t\right)g(\eta).$$

Proof of Theorem 4

$$h(x) = -\left(\int_a^x f(t)\Delta t\right)\left(\int_b^x g(t)\Delta t\right), \quad x \in [a,b].$$

Then

$$h^{\Delta}(x) = -f(x)\left(\int_{b}^{x}g(t)\Delta t\right) - \left(\int_{a}^{\sigma(x)}f(t)\Delta t\right)g(x).$$

Since h(a) = h(b) then there exist $\xi, \eta \in [a, b)$ such that

$$h^{\Delta}(\xi) \leq 0 \leq h^{\Delta}(\eta).$$

326

Hence

$$-f(\xi)\left(\int_{b}^{\xi}g(t)\Delta t\right)-\left(\int_{a}^{\sigma(\xi)}f(t)\Delta t\right)g(\xi)\leq 0\leq -f(\eta)\left(\int_{b}^{\eta}g(t)\Delta t\right)-\left(\int_{a}^{\sigma(\eta)}f(t)\Delta t\right)g(\eta),$$

which implies

$$0 \leq f(\xi) \left(\int_{b}^{\xi} g(t) \Delta t \right) + \left(\int_{a}^{\sigma(\xi)} f(t) \Delta t \right) g(\xi),$$

$$0 \geq f(\eta) \left(\int_{b}^{\eta} g(t) \Delta t \right) + \left(\int_{a}^{\sigma(\eta)} f(t) \Delta t \right) g(\eta),$$

or equivalently

$$f(\xi)\left(\int_{\xi}^{b} g(t)\Delta t\right) \leq \left(\int_{a}^{\sigma(\xi)} f(t)\Delta t\right)g(\xi),$$

$$f(\eta)\left(\int_{\eta}^{b} g(t)\Delta t\right) \geq \left(\int_{a}^{\sigma(\eta)} f(t)\Delta t\right)g(\eta).$$

The proof is complete. \Box

Corollary 3. Let $\mathbb{T} = \mathbb{R}$, from Theorem 4 together with the continuity of *f* and *g* we deduce the existence of $\gamma \in [a, b]$ such that

$$f(\gamma)\left(\int_{\gamma}^{b} g(x) \mathrm{d}x\right) = \left(\int_{a}^{\gamma} f(x) \mathrm{d}x\right) g(\gamma).$$

Theorem 5. Let f, g be continuous functions on [a, b]. Then there exist ξ , $\eta \in [a, b)$ so that

$$\left(\int_{a}^{\xi} f(t)\Delta t\right)\left(\int_{b}^{\xi} g(t)\Delta t\right) \leq f(\xi)\left(\int_{b}^{\xi} g(t)\Delta t\right) + \left(\int_{a}^{\sigma(\xi)} f(t)\Delta t\right)g(\xi)$$

and

$$\left(\int_{a}^{\eta} f(t)\Delta t\right)\left(\int_{b}^{\eta} g(t)\Delta t\right) \ge f(\eta)\left(\int_{b}^{\eta} g(t)\Delta t\right) + \left(\int_{a}^{\sigma(\eta)} f(t)\Delta t\right)g(\eta).$$

Proof of Theorem 5. Let

$$h(x) = -e_1(a,x) \left(\int_a^x f(t) \Delta t \right) \left(\int_b^x g(t) \Delta t \right).$$

Then

$$h^{\Delta}(x) = e_1(a, \sigma(x)) \left(\int_a^x f(t) \Delta t \right) \left(\int_b^x g(t) \Delta t \right) - e_1(a, \sigma(x)) \left(\left(\int_a^x f(t) \Delta t \right) \left(\int_b^x g(t) \Delta t \right) \right)^{\Delta}$$

= $e_1(a, \sigma(x)) \left(\int_a^x f(t) \Delta t \right) \left(\int_b^x g(t) \Delta t \right) - e_1(a, \sigma(x)) \left(f(x) \left(\int_b^x g(t) \Delta t \right) + \left(\int_a^{\sigma(x)} f(t) \Delta t \right) g(x) \right)$

Since h(a) = h(b) then there exists $\xi, \eta \in [a, b)$ such that

$$h^{\Delta}(\xi) \leq 0 \leq h^{\Delta}(\eta).$$

Hence

$$e_1(a,\sigma(\xi))\left(\int_a^{\xi}f(t)\Delta t\right)\left(\int_b^{\xi}g(t)\Delta t\right)-e_1(a,\sigma(\xi))\left(f(\xi)\left(\int_b^{\xi}g(t)\Delta t\right)+\left(\int_a^{\sigma(\xi)}f(t)\Delta t\right)g(\xi)\right)\leq 0,$$

and

$$e_1(a,\sigma(\eta))\left(\int_a^{\eta}f(t)\Delta t\right)\left(\int_b^{\eta}g(t)\Delta t\right)-e_1(a,\sigma(\eta))\left(f(\eta)\left(\int_b^{\eta}g(t)\Delta t\right)+\left(\int_a^{\sigma(\eta)}f(t)\Delta t\right)g(\eta)\right)\geq 0.$$

Thus

$$\left(\int_{a}^{\xi} f(t)\Delta t\right) \left(\int_{b}^{\xi} g(t)\Delta t\right) \leq f(\xi) \left(\int_{b}^{\xi} g(t)\Delta t\right) + \left(\int_{a}^{\sigma(\xi)} f(t)\Delta t\right) g(\xi)$$

and

$$\left(\int_{a}^{\eta} f(t)\Delta t\right)\left(\int_{b}^{\eta} g(t)\Delta t\right) \geq f(\eta)\left(\int_{b}^{\eta} g(t)\Delta t\right) + \left(\int_{a}^{\sigma(\eta)} f(t)\Delta t\right)g(\eta).$$

The proof is complete. \Box

Corollary 4. Let $\mathbb{T} = \mathbb{R}$, from Theorem 4 together with the continuity of f and g we deduce the existence of $\gamma \in [a, b]$ such that

$$\left(\int_a^{\gamma} f(x) dx\right) \left(\int_b^{\gamma} g(x) dx\right) = f(\gamma) \left(\int_b^{\gamma} g(x) dx\right) + \left(\int_a^{\gamma} f(x) dx\right) g(\gamma).$$

Acknowledgements

The author wishes to express gratitude to the anonymous referee(s) for a number of valuable comments and suggestions which helped to improve the presentation of the present paper from line to line.

References

- M. Bohner, G. Guseinov, Partial differential equation on time scales, Dynamic Systems and Applications 13 (2004) 351–379.
 M. Bohner, A. Peterson, Dynamic Equations on Time Series, Birkhäuser, Boston, 2001.
- [3] M. Bohner, A. Peterson, Advances in Dynamic Equations on Time Series, Birkhäuser, Boston, 2003.
- [4] S. Hilger, Ein Maβkettenkalkül mit Anwendung auf Zentrmsmannigfaltingkeiten, Ph.D. Thesis, Univarsi, Würzburg, 1988.
- [5] V. Lakshmikantham, S. Sivasundaram, B. Kaymakcalan, Dynamic Systems on Measure Chains, Kluwer Academic Publishers, 1996.

328